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2.3 a) $Z \times 3 \frac{dx}{dt} + 25x = 25 \cos 5t$ $Z \times 3 \frac{dx}{dt} + 25x = 25 \cos 5t$ $\arctanh p 5x = 5 \arctanh 3 p 5 5! \# = t$ Let $C = \arctanh 3 p 5 5!$ Solve for x to obtain $x = p 5 \tanh(5 p 5t + C)$
b) $Z \times 10 \frac{dx}{dt} + 36x = 4 \cos 2t$ $Z \times 10 \frac{dx}{dt} + 36x = 4 \cos 2t$

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Sample questions asked in the 3rd edition of System Dynamics: Consider the two-mass model shown in Figure P11.50. Use the following numerical values: $m_1 = m_2 = 1$, $k_1 = 1$, $k_2 = 4$, and $c_2 = 8$. a. Use MATLAB to obtain the root locus plot in terms of the parameter c_1 . b.

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The solution is $x(t) = -0.25e^{-2t} + 0.25 + 0.5t - e^{-3t} + 2e^{-5t}$ $[r,p,k] = \text{residue}([4,3],[1,6,34,0])$ The result is $r = [-0.0441 - 0.3735i, -0.0441 + 0.3735i, 0.0882]$, $p = [-3.0000 + 5.0000i, -3.0000 - 5.0000i, 0]$, and $k = []$. The solution is $x(t) = (-0.0441 - 0.3735j)e^{(-3+5j)t} + (-0.0441 + 0.3735j)e^{(-3-5j)t} + 0.0882$ The solution is $x(t) = 2e^{-3t} (-0.0441 \cos 5t + 0.3735 \sin 5t) + 0.0882$ (continued on the next page)

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